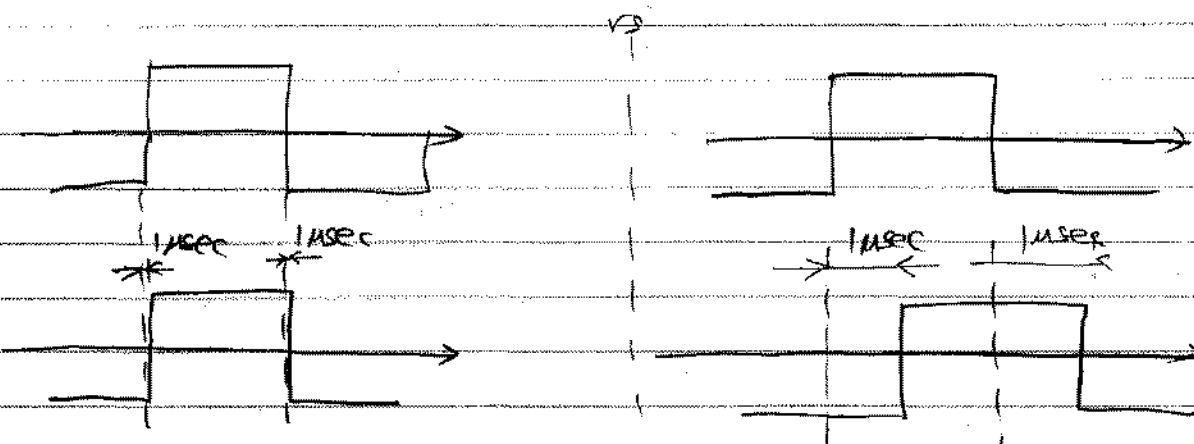


1.3 km from the base station. What is the difference in propagation delay?

A2. $\frac{300m}{3 \times 10^8 m/s} = 10^{-6} \text{ sec} = 1 \mu\text{sec}$.

1 chip delay in IS-95.

So, if the transmitted signal is a (nearly) modulated signal w/ $T \gg 1 \mu\text{sec}$ then we can set $\Delta_1 \approx \Delta_2$, while if $T \lesssim 1 \mu\text{sec}$, we can not set $\Delta_1 \approx \Delta_2$.



In summary, given the same delay profile, a wider bandwidth signal suffers more distortion.

Some people categorize wireless systems as narrowband vs. wideband according to the distortion by the multipath channel degree of

already studied

- I. $\left\{ \begin{array}{l} \text{narrowband} : \text{if excess bandwidth} \approx 0 \\ \text{wideband} : \text{if excess bandwidth} \gg 1 \end{array} \right.$
- II. $\left\{ \begin{array}{l} \text{narrowband} : \text{if delay spread} \ll 1/\text{bandwidth} \\ \text{wideband} : \text{if delay spread} \gtrsim 1/\text{bandwidth} \end{array} \right.$
- III. $\left\{ \begin{array}{l} \text{narrowband} : \text{if } f_0 \gg \text{BW} \\ \text{wideband} : \text{if } f_0 > \text{BW} \end{array} \right.$

Two path deterministic channel & frequency selectivity

• In time domain, we have $h(\xi) = \alpha_1 \delta(\xi - \Delta_1) + \alpha_2 \delta(\xi - \Delta_2)$

$$h(\xi) = \alpha_1 \delta(\xi - \Delta_1) + \alpha_2 \delta(\xi - \Delta_2)$$

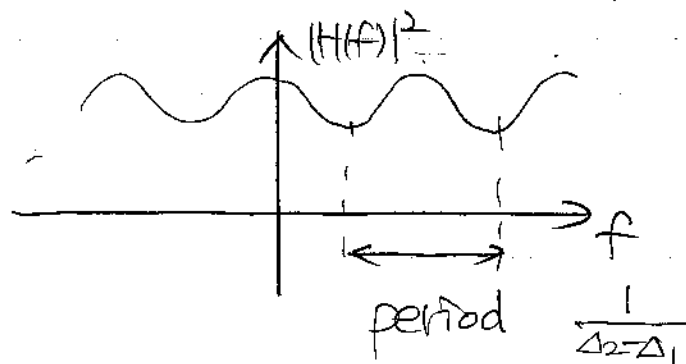
• In freq. domain

$$H(f) = \alpha_1 e^{-j2\pi f \Delta_1} + \alpha_2 e^{-j2\pi f \Delta_2}$$

$$\Rightarrow |H(f)| = |\alpha_1 + \alpha_2 e^{-j2\pi f (\Delta_2 - \Delta_1)}|$$

Note that the magnitude response depends only on the time difference $\Delta_2 - \Delta_1$!!

$$\begin{aligned} |H(f)|^2 &= |\alpha_1|^2 + |\alpha_2|^2 + 2 \operatorname{Re} \{ \alpha_1 \alpha_2^* e^{j2\pi f (\Delta_2 - \Delta_1)} \} \\ &= |\alpha_1|^2 + |\alpha_2|^2 + 2 |\alpha_1| |\alpha_2| \operatorname{Re} \{ e^{j(2\pi f (\Delta_2 - \Delta_1) + \theta)} \} \\ &= |\alpha_1|^2 + |\alpha_2|^2 + 2 |\alpha_1| |\alpha_2| \cos(2\pi f (\Delta_2 - \Delta_1) + \theta) \end{aligned}$$



• If the channel input has bandwidth $B \ll \frac{1}{\Delta_2 - \Delta_1}$ then the " looks almost flat.

$$\therefore B (\Delta_2 - \Delta_1) \ll 1 \Rightarrow \text{flat}$$

To the contrary,

$$B (\Delta_2 - \Delta_1) \gtrsim 1 \Rightarrow \text{freq. selective}$$

In summary, "bandwidth - delay spread product" determines the severity of freq. selectivity.

○ Non-resolvable multipath case

- Consider a wireless channel with channel response

$$c(\xi, t) = \alpha_0 \delta(\xi - \Delta_0) + \alpha_1 \delta(\xi - \Delta_1)$$

and the transmitted signal

$$s(t) = \text{Re} \{ S_c(t) e^{j2\pi f_c t} \}$$

Then, as we learned already, the received signal $r(t)$ is given by

$$\begin{aligned} r(t) &= \int_{-\infty}^{\infty} c(\xi, t) s(t - \xi) d\xi \\ &= \alpha_0 s(t - \Delta_0) + \alpha_1 s(t - \Delta_1) \\ &= \alpha_0 \text{Re} \{ S_c(t - \Delta_0) e^{j2\pi f_c (t - \Delta_0)} \} \\ &\quad + \alpha_1 \text{Re} \{ S_c(t - \Delta_1) e^{j2\pi f_c (t - \Delta_1)} \} \\ &= \text{Re} \{ (\alpha_0 e^{-j2\pi f_c \Delta_0} + \alpha_1 e^{-j2\pi f_c \Delta_1}) S_c(t - \Delta) e^{j2\pi f_c t} \} \end{aligned}$$

If $|\Delta_0 - \Delta_1| \ll \text{bandwidth of } S_c(t)$. ($\Delta \triangleq \Delta_0 \approx \Delta_1$)

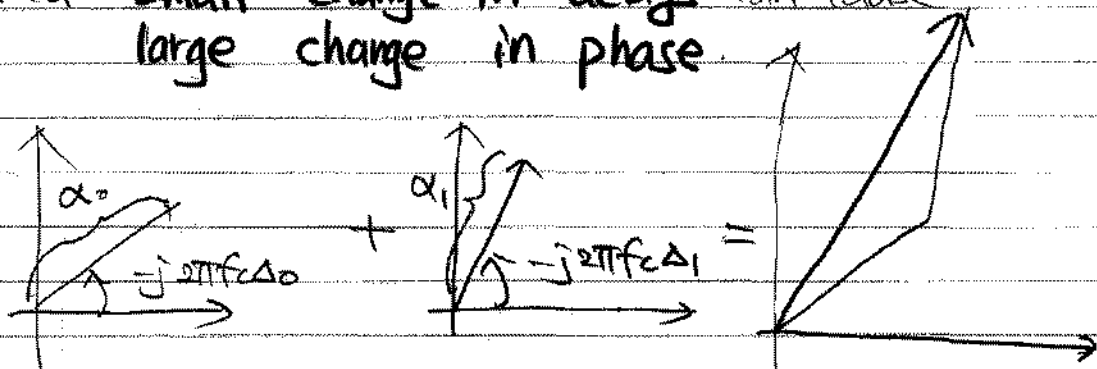
- Although the narrowband signal assumption made it possible to combine two multipath components into a single delay signal, the complex gain

$$\alpha_0 e^{-j2\pi f_c \Delta_0} + \alpha_1 e^{-j2\pi f_c \Delta_1}$$

cannot be combined as $\approx (\alpha_0 + \alpha_1) e^{-j2\pi f_c \Delta}$ because $f_c \Delta_0$ can be significantly different from $f_c \Delta_1$.

ex $f_c = 1 \text{ GHz}$, $\Delta_0 - \Delta_1 = 10^{-9} \text{ sec} \Rightarrow f_c \Delta_0 - f_c \Delta_1 = 10^3$.

- Note that small change in delay can cause large change in phase.



- We here in a non-resolvable multipath case have a dilemma.

$$\Delta \approx \Delta_0 \approx \Delta_1 \approx \Delta_2 \approx \dots \approx \Delta_{N-1}$$

holds for $S_e(t - \Delta_n) \approx S_e(t - \Delta)$, it does not hold for

$$\left\{ e^{-j2\pi f c \Delta_n} \right\}_{n=0}^{N-1}$$

- In case we have a very large number of non-resolvable multipath, the central limit theorem is often resorted to.

The claim is that let's model that α_n 's are random variables & that $2\pi f c \Delta_n$'s are i.i.d. uniform random variables on $[0, 2\pi)$.

Then, it would be OK to approximate

$$\sum_{n=0}^{N-1} \alpha_n e^{j2\pi f c \Delta_n}$$

as a proper-complex Gaussian random variable with mean zero.

$$\therefore r(t) = \text{Re} \left\{ \alpha S_e(t - \Delta) e^{j2\pi f c t} \right\}$$

$$\alpha \sim \mathcal{CN}(0, \sigma_\alpha^2)$$

a uniform random variable

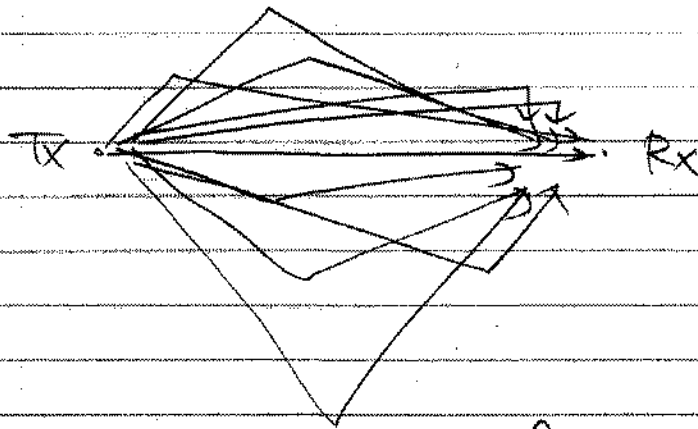
$$= \text{Re} \left\{ \underbrace{|\alpha|}_{\text{a Rayleigh random variable}} e^{j2\alpha} \text{Sinc}(\Delta) e^{j2\pi f_c t} \right\}$$

a Rayleigh random variable

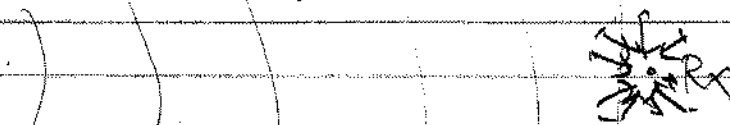
- If a LOS dominates, then Rician approximation is often used.

○ Motion & Fading

- We've just seen that the case with large non-resolvable multipaths enable us to model the complex channel gain as a proper-complex Gaussian r.v.



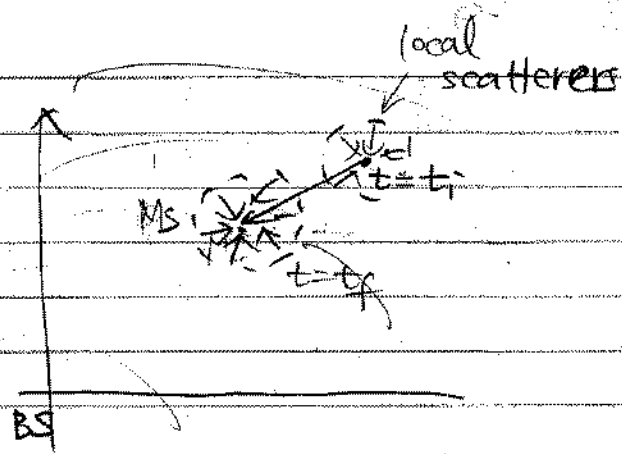
This occurs in wireless channel where ^{many} scatterers are very close to the RX, so that delay spread is very small among multiple paths, which



is the case in cellular downlink. (BS → MS)

- Now, what if the RX is in motion?

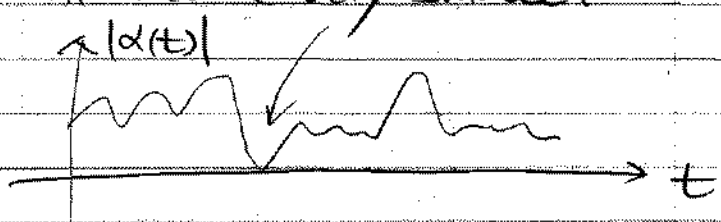
We can easily guess that the complex gain now becomes a random process that varies as a function of time.



$\alpha(t_i)$
 $\alpha(t_f)$

If a large # of multipaths these may be well approximated as proper-complex WSS random process.

- If the multipath components interfere destructively, $|\alpha(t)|$ will become very small.



"fade-in fade-out" channel \rightarrow fading channel.

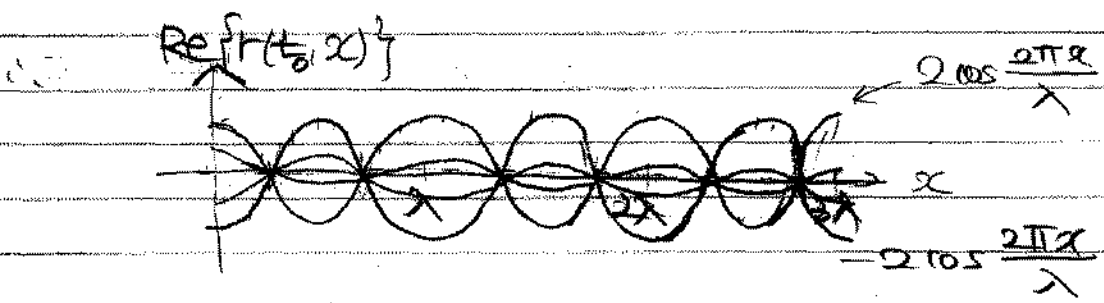
- Channel fading (magnitude fluctuation) is due to the motion of
 T_x ,
 R_x , or
 scatterers

and at least two different non-resolvable propagation paths.

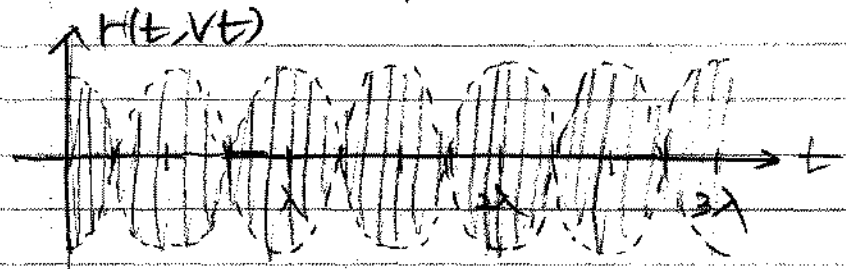
- Ex/ Two-path fading channel

Suppose the received signal $r(t, x)$ is given by

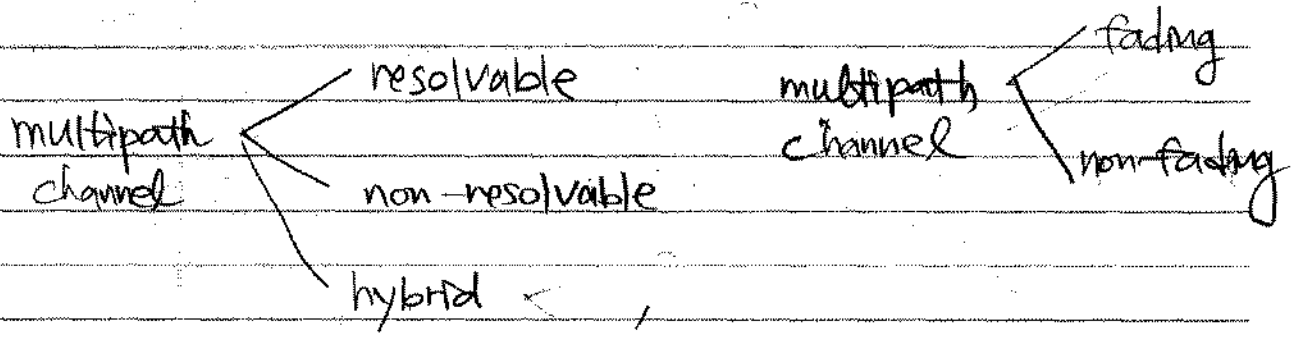
$$\begin{aligned}
 r(t, x) &= \exp\{j2\pi(fct - \frac{x}{\lambda})\} + \exp\{j2\pi(fct + \frac{x}{\lambda})\} \\
 &= \exp(j2\pi fct) 2 \cos(2\pi \frac{x}{\lambda})
 \end{aligned}$$



If the Rx moves slowly from $x=0$ to $x=3\lambda$ then, the received signal will look like



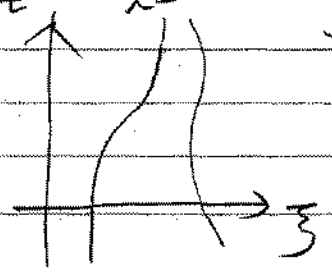
This shows only two paths and a motion is enough to cause channel fading.



Summary

Fading phenomenon can be incorporated in $C_2(\xi, t)$ model, e.g. as

$$C_2(\xi, t) = \alpha_0(t) \delta(\xi - \Delta(t)) + \alpha_1(t) \delta(\xi - \Delta_1(t))$$



time-varying coefficients due to multipath fading

- The key words are multipaths and motion.
- In the next note, we consider statistical modeling of $C(\xi, t)$.

