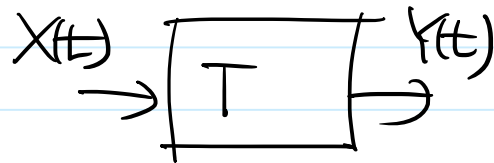


□ Ann.

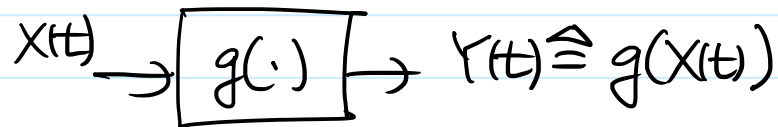
- Exam #2. claim within a week
- HW #11. will be assigned soon

□ Review



mapping rule $\begin{cases} \text{deterministic} \\ \text{random} \end{cases}$

§ 9-2-1 Memoryless System



□ Full description of $\{Y(t)\}$?

$$(i) f_{Y(t)}(y) = \dots$$

$$(ii) \underbrace{f_{Y(t_1), Y(t_2)}}_{Y_1, Y_2}(y_1, y_2) = \sum_i \frac{f_{X(t_1), X(t_2)}(x_{1i}, x_{2i})}{|J(x_{1i}, x_{2i})|}$$

$$(iii) f_{Y(t_1), Y(t_2), \dots, Y(t_n)}(y_1, y_2, \dots, y_n) = \sum_i \frac{f_{X(t_1), X(t_2), \dots, X(t_n)}(x_{1i}, x_{2i}, \dots, x_{ni})}{|g'(x_{1i}) g'(x_{2i}) \dots g'(x_{ni})|}$$

$$\begin{bmatrix} Y_1 \\ Y_2 \end{bmatrix} = \begin{bmatrix} g(x_1) \\ g(x_2) \end{bmatrix}$$

$$\det \begin{bmatrix} \frac{dg}{dx_1} & 0 \\ 0 & \frac{dg}{dx_2} \end{bmatrix}$$

□ Expectation & Moments

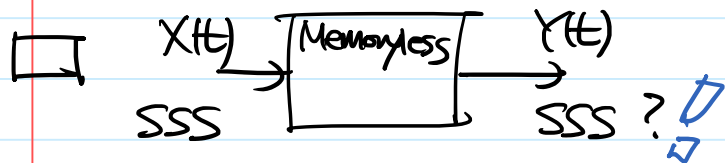
$$\begin{aligned}\mu_Y(t) &\triangleq E\{Y(t)\} = \int_{-\infty}^{\infty} y f_{Y(t)}(y) dy \\ &= E\{g(X(t))\} = \int_{-\infty}^{\infty} g(x) f_{X(t)}(x) dx.\end{aligned}$$

$R_{XX}(t_1, t_2)$

$$R_{XY}(t_1, t_2) = E\{X(t_1) Y(t_2)\} = E\{\underbrace{X(t_1)}_{x_1} \underbrace{g(X(t_2))}_{x_2}\} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x_1 g(x_2) f_{X(t_1)X(t_2)}(x_1, x_2) dx_1 dx_2$$

$R_{YX}(t_1, t_2)$

$R_{YY}(t_1, t_2)$



$$\underline{t} \in \mathbb{R}^N \quad \underline{Y}(\underline{t}) \triangleq \begin{bmatrix} Y(t_1) \\ \vdots \\ Y(t_N) \end{bmatrix} = \begin{bmatrix} g(X(t_1)) \\ \vdots \\ g(X(t_N)) \end{bmatrix} \triangleq \underline{g}(X(\underline{t}))$$

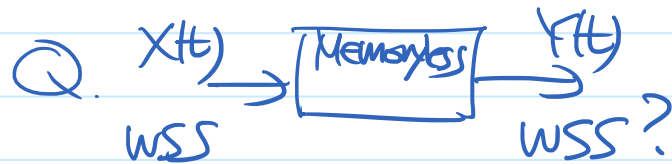
$$\text{LHS} = \int_{\underline{x} \in \mathbb{R}^N} e^{j \underline{\omega}^T \underline{g}(\underline{x})} f_{X(\underline{t})}(\underline{x}) d\underline{x}$$

$$\text{RHS} = \int_{\underline{x} \in \mathbb{R}^N} e^{j \underline{\omega}^T \underline{g}(\underline{x})} f_{X(\underline{t})}(\underline{x}) d\underline{x}$$

$$\underline{t} + \underline{\tau} \triangleq \underline{t} + \underline{\tau} \underline{1}$$

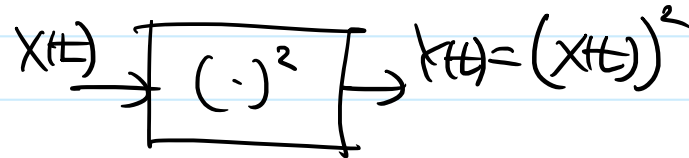
$$\Phi_{Y(\underline{t})}(\underline{\omega}) = \Phi_{Y(\underline{t} + \underline{\tau})}(\underline{\omega}), \quad \forall \underline{\omega}$$

$$\begin{aligned} &\Downarrow \\ &E\{e^{j \underline{\omega}^T Y(\underline{t})}\} \\ &= E\{e^{j \underline{\omega}^T g(X(\underline{t}))}\} \end{aligned} \quad \Downarrow \quad \begin{aligned} &E\{e^{j \underline{\omega}^T Y(\underline{t} + \underline{\tau})}\} \\ &= E\{e^{j \underline{\omega}^T g(X(\underline{t} + \underline{\tau}))}\} \end{aligned}$$

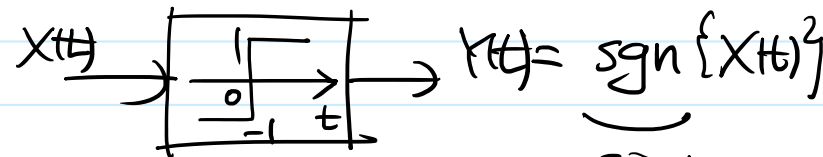


Examples

— square-law device



— hard limiter



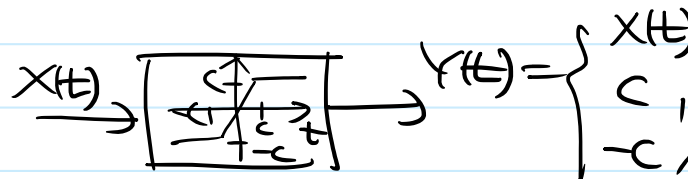
signum
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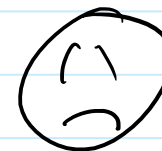
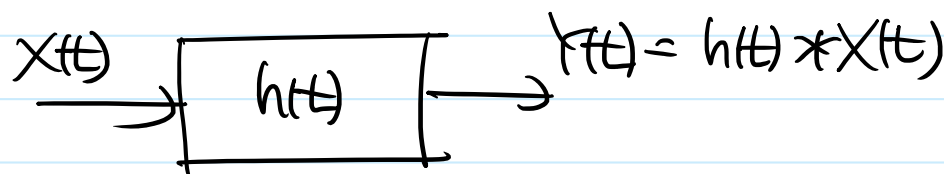
$$\text{sign}(x) = \begin{cases} 1 & x > 0 \\ 0 & x = 0 \\ -1 & x < 0 \end{cases}$$

$$\begin{aligned} E\{Y(t)\} &= 1 \times \Pr(X(t) > 0) \\ &\quad + (-1) \times \Pr(X(t) < 0) \\ &= 1 - \Pr(X(t) \leq 0) - \Pr(X(t) < 0) \\ &= 1 - 2F_{X(t)}(0) \end{aligned}$$

— limiter

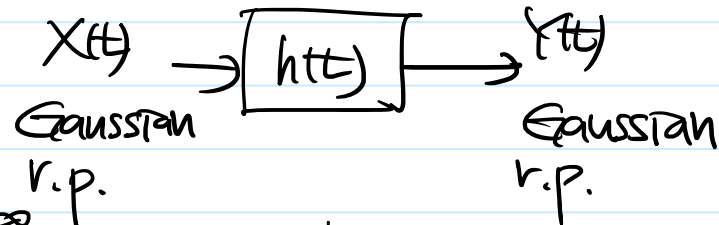


§9-2-2 LTI systems



$X(t)$ full characterization (o)
 $Y(t)$ " " (x)
 in general.

□ $X(t)$ is Normal.
 $\Rightarrow Y(t)$ is Normal.



$$Y(t) = h(t) * X(t) = \int_{-\infty}^{\infty} h(\tau) X(t-\tau) d\tau$$

$$\approx \sum_i h(\tau_i) X(t-\tau_i) \Delta \tau$$

$$\square \mu_Y(t) = E\{Y(t)\} = E\{h(t) * X(t)\} = E\left\{\int_{-\infty}^{\infty} h(\tau) \underbrace{X(t-\tau)}_{\mu_X(t-\tau)} d\tau\right\} = \int_{-\infty}^{\infty} h(\tau) \mu_X(t-\tau) d\tau$$

$$= h(t) * \mu_X(t). \quad ?!$$

$$R_{YY}(t_1, t_2) = E\{\underbrace{Y(t_1)}_{h(t_1) * X(t_1)} \underbrace{Y(t_2)}_{h(t_2) * X(t_2)}\} = E\{h(t_1) * X(t_1) \underbrace{h(t_2) * X(t_2)}_{\text{blue asterisk}}\}$$

$$= E\left\{\int_{-\infty}^{\infty} h(\tau_1) X(t_1 - \tau_1) d\tau_1 \underbrace{\int_{-\infty}^{\infty} h(\tau_2) X(t_2 - \tau_2) d\tau_2}_{\text{blue asterisk}}\right\}$$

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} h(\tau_1) E\{X(t_1 - \tau_1) \underbrace{X(t_2 - \tau_2)}_{\text{blue asterisk}}\} \underbrace{h(\tau_2)}_{\text{blue asterisk}} d\tau_1 d\tau_2$$

$$= h(t_1) * (X(t_1) X(t_2)) * h(t_2) = h(t_1) * R_{XX}(t_1, t_2) * \underbrace{h(t_2)}_{\text{blue asterisk}}.$$

$$R_{XY}(t_1, t_2) = R_{XX}(t_1, t_2) * \underbrace{h(t_2)}_{\text{blue asterisk}}$$

$$R_{YX}(t_1, t_2) = \underbrace{h(t_1)}_{\text{blue asterisk}} * R_{XX}(t_1, t_2).$$

$\square$ If $X(t)$ is Gaussian w/ $\mu_X(t), R_{XX}(t_1, t_2)$, then $Y(t)$ " " w/ $\mu_Y(t) = h(t) * \mu_X(t)$, $R_{YY}(t_1, t_2) = h(t_1) * R_{XX}(t_1, t_2) * h(t_2)$.

full char. full char.

$\square$ If $X(t)$ is WSS, $\mu_X(t) = \mu_X, \forall t$. $R_{XX}(t+\tau, t) = R_{XX}(\tau), \forall \tau, t$.
 then $Y(t)$ is WSS. $\mu_Y(t) = h(t) * \mu_X(t) = \mu_X \int_{-\infty}^{\infty} h(\tau) d\tau = \mu_X H(0)$

$$R_{YY}(t_1, t_2) =$$

$$R_{YY}(t+\tau, t) = \dots \text{ f.t. of } \tau.$$

$$\begin{aligned}
 R_{YY}(t_1, t_2) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} h(\tau_1) R_{XX}(t_1 - \tau_1, t_2 - \tau_2) h(\tau_2) d\tau_1 d\tau_2 \\
 R_{YY}(t+\tau, t) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} h(\tau_1) R_{XX}(t+\tau - \tau_1, t - \tau_2) h(\tau_2) d\tau_1 d\tau_2 = \underbrace{(h(\tau) * R_{XX}(\tau))}_{= R_{XX}(\tau - \tau_1 + \tau_2)} * h(-\tau)
 \end{aligned}$$

claim

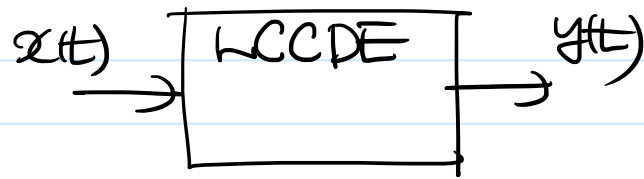
$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} h(\tau_1) R_{XX}(\tau_1 - \tau_2) h(\tau_2) d\tau_1 d\tau_2 * h(-\tau) d\tau$$

$\tau_1 - \tau_2$

$\square$ White n.p. $X(t)$

non-WSS	$R_{XX}(t_1, t_2) = f(t_1) \delta(t_1 - t_2)$
WSS	$R_{XX}(\tau) = f \delta(\tau)$

§ 9-2-3 Differential Equations.



$$\sum_k a_k y^{(k)}(t) = \sum_l b_l x^{(l)}(t)$$

Q1. Is this system LTI?

A1. No, in general,

Yes if initial rest (zero input zero output)

Q2. ^{Any} $h(t)$ can be synthesized by an LCCDE?

A2. No, in general.