

Review

- zero-error variable-length } source coding
- arbitrarily small-error } fixed-length
- Shannon's information measures

lex/ $H(X, Y) = H(X) + H(Y|X)$

$$E \left\{ \log \frac{1}{P_{XY}(X, Y)} \right\} = E \left\{ \log \frac{1}{P_X(X)} \right\}$$

$$+ E \left\{ \log \frac{1}{P_{Y|X}(Y|X)} \right\}$$

$$E \left\{ \log \frac{1}{P_{Y|X}(Y|X)} \right\} = E \left[E \left\{ \log \frac{1}{P_{Y|X}(Y|X)} \mid X \right\} \right]$$

$$= E \{ f(X) \}$$

$$\text{where } f(x) = E \left\{ \log \frac{1}{P_{Y|X}(Y|X)} \mid X=x \right\}$$

$$\triangleq H(Y|X=x)$$

$$D(P_X \| P_Y) \geq 0 \dots$$

$$H(X|\hat{X}) \leq \text{a function of } P_{\hat{X}}(\hat{X})$$

$$X \rightarrow Y \rightarrow Z \Rightarrow I(X; Y) \geq I(X; Z)$$

- Channel coding for DMC

$$C = \max_{p_X(x)} I(X; Y)$$

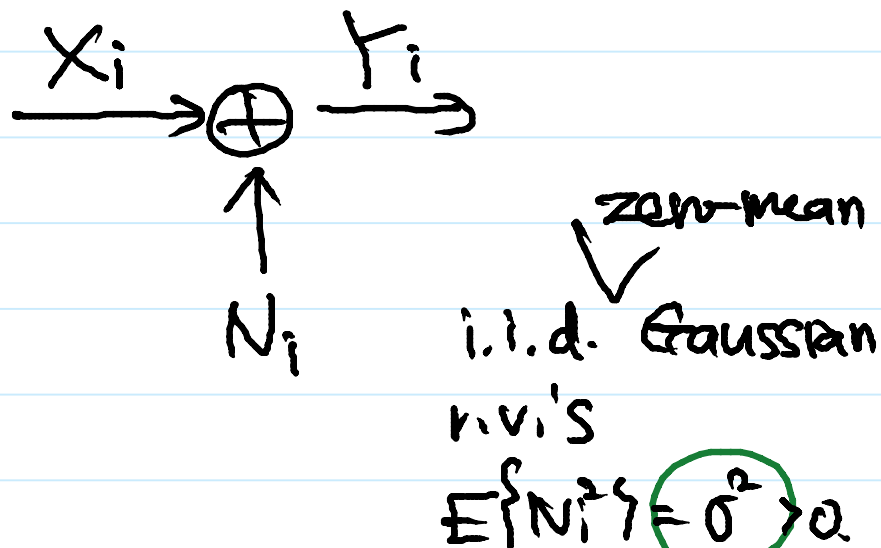
< $C_{FB} = C$ causal
layered system noiseless

→ simple.
(extreme).

- Channel coding for CMC

↑ AWGN channel

- Discrete-Time Additive White Gaussian Noise Channel



$$C = \max_{p_X(x)} I(X; Y)$$

$$\text{s.t. } E\{X^2\} \leq P$$

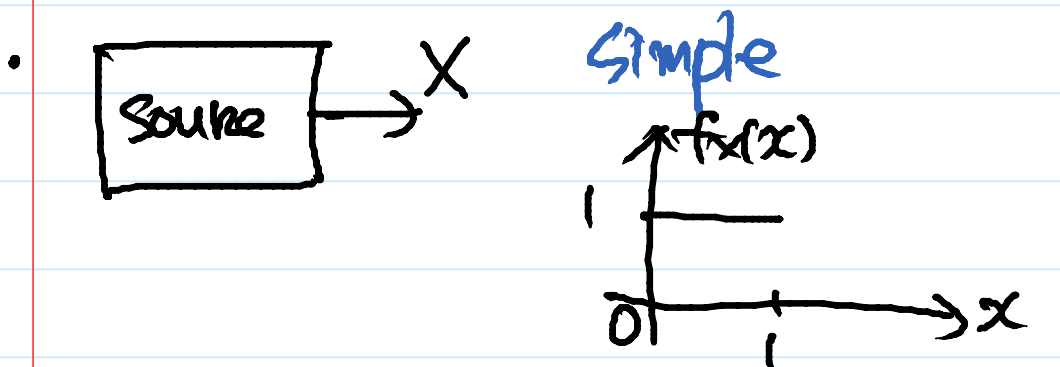
SNR.

$$\text{If AWGN} = \frac{1}{2} \log \left(1 + \frac{P}{\sigma^2} \right) \text{ [bits/c.u]}$$

$$C = \sup_{f_{X^A}} I(X^A; Y^A) \\ \text{s.t. } E[X^2] \leq P.$$

- Given a r.v. X , X is $\sqrt{f_X(x)}$ of x
 - continuous if $F_X(x)$ is a continuous
 - discrete if $F_X(x)$ is piecewise const.
 - mixed if $F_X(x)$

where $F_X(x) \triangleq \Pr(X \leq x)$



$$1/3 = 0.333 \dots$$

$$1/2 = ?$$

$$H(X) = +\infty.$$

extension
(consistency,
backward
compatibility)

- Given a continuous r.v. X , we define a discrete r.v. X^Δ .

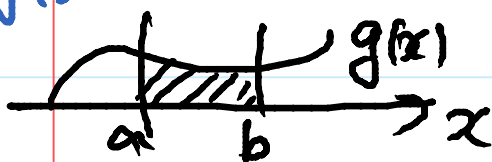


$$\Pr(a \leq X \leq b) = F_X(b) - F_X(a) \text{ when } X \text{ is continuous.}$$

Now,

$$H(X^\Delta) = \sum_{i=-\infty}^{\infty} (F_X(\Delta_{i+1}) - F_X(\Delta_i)) \log \frac{1}{F_X(\Delta_{i+1}) - F_X(\Delta_i)}$$

Visualized $\approx \sum_{i=-\infty}^{\infty} f_X(\Delta_i) \Delta \log \frac{1}{f_X(\Delta_i) \Delta}$



$$\int_a^b g(x) dx \approx \lim_{N \rightarrow \infty} \sum_{n=1}^N g\left(a + \frac{(n-1)(b-a)}{N}\right) \frac{1}{N}$$

$$= \lim_{\Delta \rightarrow 0} \sum_{n=1}^N g(\Delta_n) \Delta$$

$$= \sum_{i=0}^{\infty} g(\Delta_i) \Delta$$

$$= \sum_{i=1}^n f_X(\Delta_i) \log \frac{1}{f_X(\Delta_i)} \Delta t$$

$$\sum_{i=-\infty}^{\infty} f_X(\Delta_i) \Delta \log \frac{1}{\Delta}$$

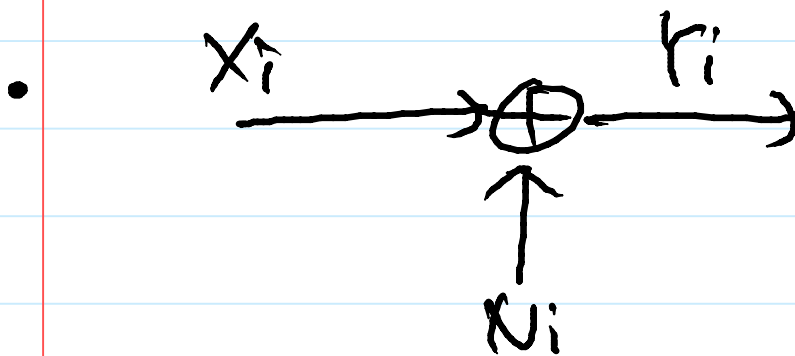
$$H(X^\Delta) \rightarrow \int_{-\infty}^{\infty} f_X(x) \log \frac{1}{f_X(x)} dx + \infty$$

$$\text{as } \Delta \rightarrow 0$$

$$\triangleq h(X)$$

$$\triangleq E\left\{\log \frac{1}{f_X(x)}\right\}$$

differential entropy.



- Given jointly random two cont. r.v.'s X and Y , consider

$$I(X^\Delta; Y^\Delta) = H(X^\Delta) + H(Y^\Delta) - H(X^\Delta, Y^\Delta)$$

$$= h(X) + \sum_i f_X(\Delta_i) \Delta \log \frac{1}{\Delta} + h(Y) + \sum_j f_Y(\Delta_j) \Delta \log \frac{1}{\Delta} - h(X, Y) - \sum_i \sum_j f_{X,Y}(\Delta_i, \Delta_j) \Delta \log \frac{1}{\Delta}$$

($f_{X,Y}(\Delta_{i+1}, \Delta_{j+1}) - f_{X,Y}(\Delta_i, \Delta_{j+1}) - f_{X,Y}(\Delta_{i+1}, \Delta_j) + f_{X,Y}(\Delta_i, \Delta_j)$) $\approx f_{X,Y}(\Delta_i, \Delta_j)$)

$$\log \frac{1}{\Delta^2} \hat{\mathbb{E}}_{\mathbf{x} \sim \mathcal{D}} \mathbb{E}_{\mathbf{y} \sim \mathcal{D}} \left[\sum_{i,j} f_{x,y}(\Delta_i, \Delta_j) \right]$$

$$\begin{aligned}
H(X^\Delta, Y^\Delta) &\cong \sum_i \sum_j f_{X,Y}(\Delta_i, \Delta_j) \Delta^2 \log \frac{1}{f_{X,Y}(\Delta_i, \Delta_j) \Delta^2} \\
&= \sum_i \sum_j f_{X,Y}(\Delta_i, \Delta_j) \log \frac{1}{f_{X,Y}(\Delta_i, \Delta_j)} \Delta^2 \\
&\quad + \sum_i \sum_j f_{X,Y}(\Delta_i, \Delta_j) \log \frac{1}{\Delta^2} \cdot \Delta^2 \\
&= \iint f_{X,Y}(x,y) \log \frac{1}{f_{X,Y}(x,y)} dx dy \\
&\quad + \sum_i \sum_j f_{X,Y}(\Delta_i, \Delta_j) \log \frac{1}{\Delta^2} \Delta^2
\end{aligned}$$

$$\begin{aligned}
I(X^\Delta; Y^\Delta) &\rightarrow h(X) + h(Y) - h(X, Y) \\
&\quad \text{as } \Delta \rightarrow 0 \quad \cong I(X; Y)
\end{aligned}$$

$$\begin{aligned}
I(X; Y) &= -E \left\{ \log \frac{f_X(X) f_Y(Y)}{f_{X,Y}(X, Y)} \right\} \\
&= h(X) - h(X|Y) \\
&\quad \text{where } h(X|Y) = E \left\{ \log \frac{1}{f_{X|Y}} \right\} \\
&= h(Y) - h(Y|X).
\end{aligned}$$

$$\begin{aligned}
&\cdot h(X), h(Y), h(X, Y) \\
&h(X|Y), h(Y|X), I(X; Y)
\end{aligned}$$