

Lec. 22

Announcements

1. Two make-ups on this Friday
2. 2nd midterm exam on Next Friday

Review

$$\min_{\hat{\theta}(\underline{y})} E_{\underline{\theta}} \{ \|\hat{\theta}(\underline{Y}) - \underline{\theta}\|^2 \}, \forall \underline{\theta}. \quad \left\{ \begin{array}{l} \text{MVUE} \\ \text{UMVU estimator} \end{array} \right.$$

$$\text{s.t.} \quad E_{\underline{\theta}} \{ \hat{\theta}(\underline{Y}) - \underline{\theta} \} = \underline{0}, \forall \underline{\theta}$$

$$\hat{\theta}(\underline{y}) = W \underline{y} \quad \longleftarrow \text{BLUE}$$

PR

$f_{Y; \theta_0}(y)$



$f_{Y; \theta_1}(y)$



$f_{Y; \theta}(y)$

not a ft of θ ,
 $\forall y$.

$f_{Y|T(Y); \theta_0}(y|t)$

$f_{Y|T(Y); \theta_1}(y|t)$

not a ft of
 θ , $\forall y, \forall t$.

a statistic

a sufficient statistic

θ random $\Rightarrow$

$T(Y)$ $\Rightarrow$
sufficient.

$f_{\theta|Y}(\theta|y)$ is a ft only
of θ and $T(y)$.

p.3 Neyman-Fischer Factorization Theorem.

Given a family $\{f_{\underline{X}; \underline{\theta}}(\underline{y}) : \underline{\theta} \in A\}$ of
distribution functions,

$\underline{T}(\underline{X})$ is sufficient for $\underline{\theta}$

$\Leftrightarrow \exists h(\underline{y}), g(\underline{t}, \underline{\theta})$, and $\underline{T}(\underline{y})$ such that

$$f_{\underline{X}; \underline{\theta}}(\underline{y}) = h(\underline{y}) g(\underline{T}(\underline{y}), \underline{\theta}), \quad \forall \underline{y} \forall \underline{\theta} \in A.$$

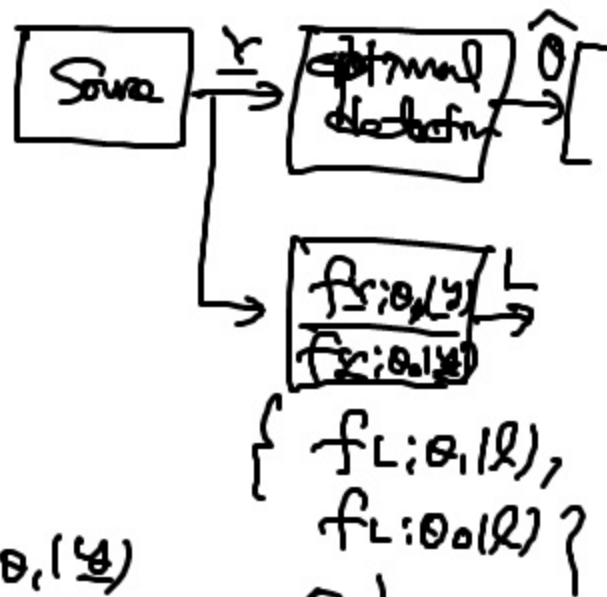
p.4 $\{f_{Y; \theta_0}(y), f_{Y; \theta_1}(y)\}$

$$f_{Y; \theta}(y) = h(y) g(\underline{T}(y), \theta)$$

$$\left(\underline{T}(y) = \frac{f_{Y; \theta_1}(y)}{f_{Y; \theta_0}(y)} \right)$$

$$= f_{Y; \theta_0}(y) g\left(\frac{f_{Y; \theta_1}(y)}{f_{Y; \theta_0}(y)}, \theta\right)$$

where $g(t, \theta) = \begin{cases} t & , \theta = 1 \\ 1 & , \theta = 0 \end{cases}$



p.5.

$$E_{\underline{\theta}}\{g(\underline{Y})\} = 0, \forall \underline{\theta}$$

$$\Leftrightarrow \int_{\underline{y}} g(\underline{y}) f_{\underline{Y}; \underline{\theta}}(\underline{y}) d\underline{y} = 0, \forall \underline{\theta}$$

$$\Rightarrow g(\underline{Y}) = 0 \text{ a.s. } \forall \underline{\theta}$$

$$\Leftrightarrow P_{\underline{\theta}}(g(\underline{Y}) = 0; \underline{\theta}) = 1, \forall \underline{\theta}$$

p.6

$$E_\theta[g(Y)] = 0, \forall \theta$$

$$\Leftrightarrow \int_{-\infty}^{\infty} g(y) \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(y-\theta)^2}{2}\right) dy = 0, \forall \theta$$

$$\Rightarrow \int_{-\infty}^{\infty} \boxed{g(y)} \cdot \boxed{\frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(y-\theta)^2}{2}\right)} \cdot e^{\theta} \cdot \cancel{e^{-\frac{(y-\theta)^2}{2}}} dy = 0, \forall \theta$$

$\Rightarrow$ Laplace transform of

$$\int f(x) e^{-sx} dx.$$

$$g(y) e^{-\frac{(y-\theta)^2}{2}}$$

$$\therefore \cancel{g(y) e^{-\frac{(y-\theta)^2}{2}}} = 0, \forall y.$$

p-7 Given $\{f_1, f_2, \dots, f_n\}$,

$$\underline{g}^T \underline{f}_n = 0, \forall n \Rightarrow \underline{g} = \underline{0}.$$

lex/ $\underline{g} \in \mathbb{R}^{N \times 1}$

1. $\{\underline{e}_1, \underline{e}_2, \dots, \underline{e}_N\}$

2. $\{\underline{e}_1, \underline{e}_2\}$

complete family

Exponential Family.

$$\{ \exp(\int \underline{f}_x(\underline{g}) d\underline{x}) \}$$

p. 8

$$f_{\underline{Y}; \underline{\theta}}(\underline{y}) = h(\underline{y}) c(\underline{\theta}) e^{\underbrace{Q_1(\underline{\theta}) T_1(\underline{y})}_{\circ} + \underbrace{Q_2(\underline{\theta}) T_2(\underline{y})}_{\circ} + \dots + \underbrace{Q_M(\underline{\theta}) T_M(\underline{y})}_{\circ}}$$

$$= h(\underline{y}) c(\underline{\theta}) e^{\underbrace{\theta_1 \cdot 0}_{\circ}} e^{\underbrace{\theta_2 \cdot 0}_{\circ}} e^{\underbrace{\theta_3 \cdot 0}_{\circ}} \dots e^{\underbrace{\theta_N \cdot 0}_{\circ}} e^{\underbrace{Q_1(\underline{\theta}) T_1(\underline{y})}_{\circ}} e^{\underbrace{Q_2(\underline{\theta}) T_2(\underline{y})}_{\circ}} \dots e^{\underbrace{Q_M(\underline{\theta}) T_M(\underline{y})}_{\circ}}$$

$$\underline{\theta}' = \begin{bmatrix} \theta_1 \\ \theta_2 \\ \vdots \\ \theta_N \\ Q_1(\underline{\theta}) \\ \vdots \\ Q_M(\underline{\theta}) \end{bmatrix}$$

$$= f_{\underline{Y}; \underline{\theta}'}(\underline{y}), \quad \underline{T}'(\underline{y}) = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ T_1(\underline{y}) \\ \vdots \\ T_M(\underline{y}) \end{bmatrix}$$

Reparameterize