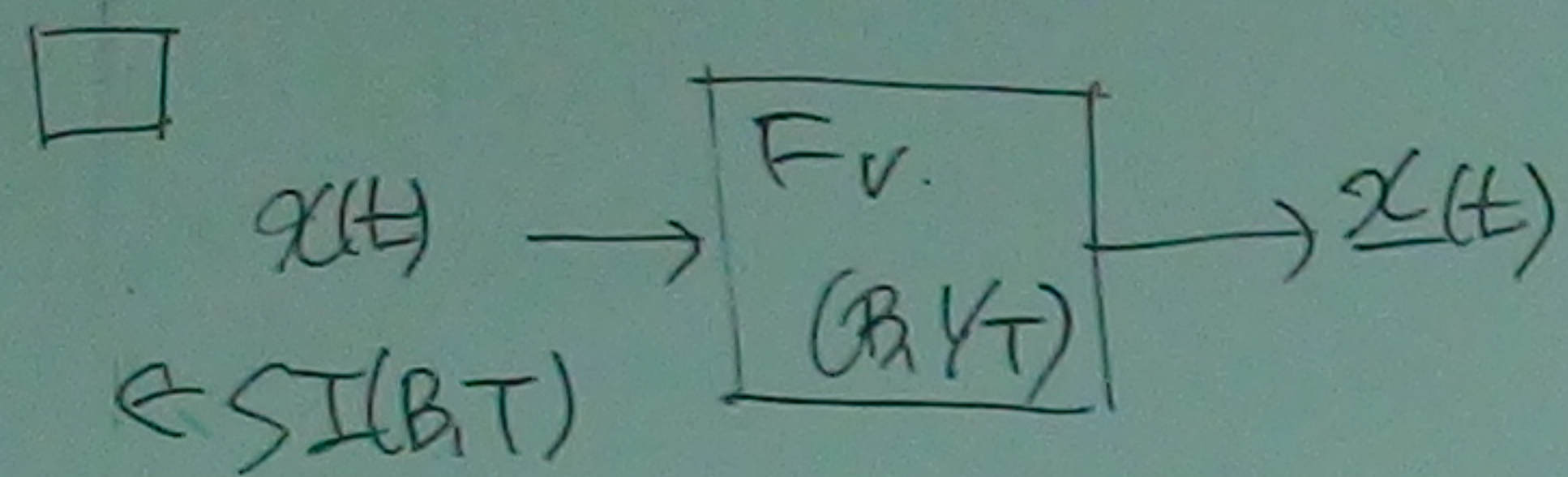




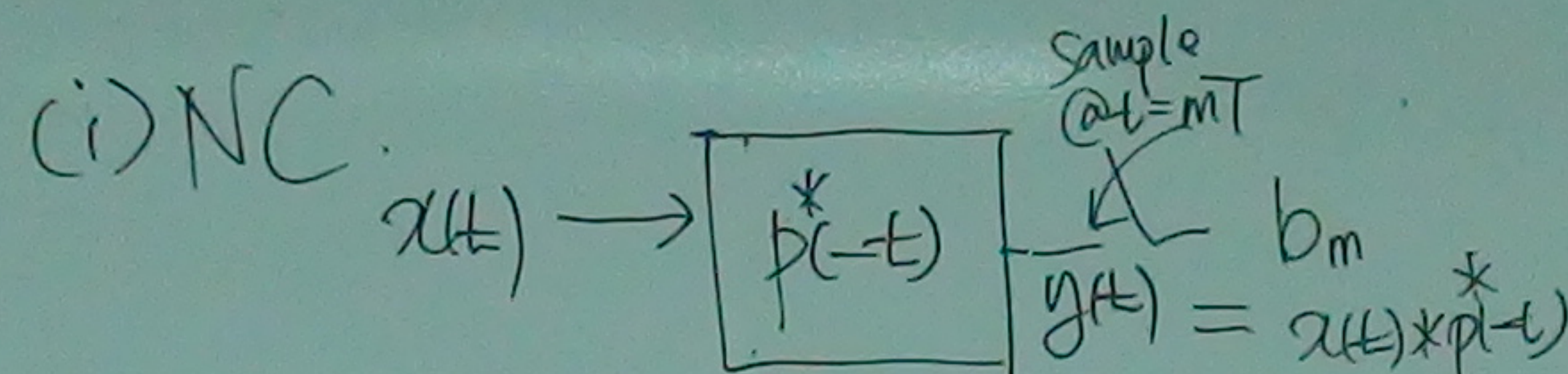
□ Nyquist Criterion. $\begin{matrix} NC \\ GNC \end{matrix}$ generator

$$x(t) = \sum_k \sum_n b_{nk} p_k(t-nT)$$

$$x(t) = \sum_k \sum_n b_{nk} p_k(t-nT)$$

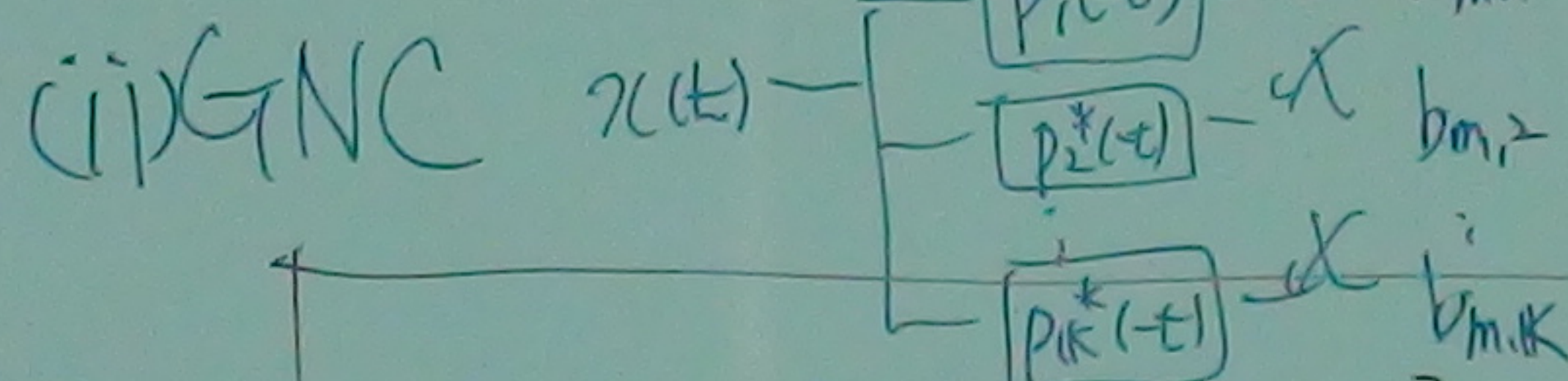
$$p_k(f) = \mathcal{F}\{p_k(t)\} \quad \text{VFT of } p_k(t)$$

$$x(f) = \sum_k \sum_n b_{nk} p_k(f) e^{-j2\pi f n T}$$



$$\Leftrightarrow b_m = \int_{-\infty}^{\infty} x(t) p^*(t-mT) dt$$

$$= x(t) * p^*(-t) \Big|_{t=mT} \quad \text{sample at } t=mT$$



Q. What properties?

Linear
 $x(t) \rightarrow \begin{bmatrix} \text{FRESH} \\ \text{vec} \\ (B/T) \end{bmatrix} \rightarrow x(t) = \sum_{k=1}^K \sum_{n=-\infty}^{\infty} b_{kn} p_k(t-nT)$
 $\in SI(BT)$

$$p_k(t) \xrightarrow{F_v} p_k(f)$$

$$p_k(t-nT) \xrightarrow{F_v} p_k(f) e^{-j2\pi f n T}$$

$$\int_{-\infty}^{\infty} p_k(t-mT) p_k^*(t-nT) dt = \delta[k-k'] \delta[m-m']$$

$$P(f) = [p_1(f) \dots p_K(f)]$$

$$\frac{1}{T} P^H(f) P(f) = I_K, \forall f$$

$$\Leftrightarrow \frac{1}{T} \sum_k |p_k(f - \frac{k}{T})|^2 = 1, \forall f$$

$$\Leftrightarrow \frac{1}{T} \sum_k p_k^*(f - \frac{k}{T}) p_k(f - \frac{k}{T}) = \delta_{ij}$$

$$y(mT) = \int_{-\infty}^{\infty} p^*(-t-mT) x(t) dt$$

$$= \int_{-\infty}^{\infty} p^*(f) e^{j2\pi f m T} x(f) df$$

$$= b_m$$

$$= \int_{-\infty}^{\infty} p^*(f) e^{j2\pi f m T} \sum_{n=-\infty}^{\infty} b_n p(f) e^{-j2\pi f n T} df$$

$$\Leftrightarrow \sum_{n=-\infty}^{\infty} b_n \int_{-\infty}^{\infty} (p^*(f) p(f)) e^{j2\pi f (m-n) T} df$$

$$= \delta[m-n]$$

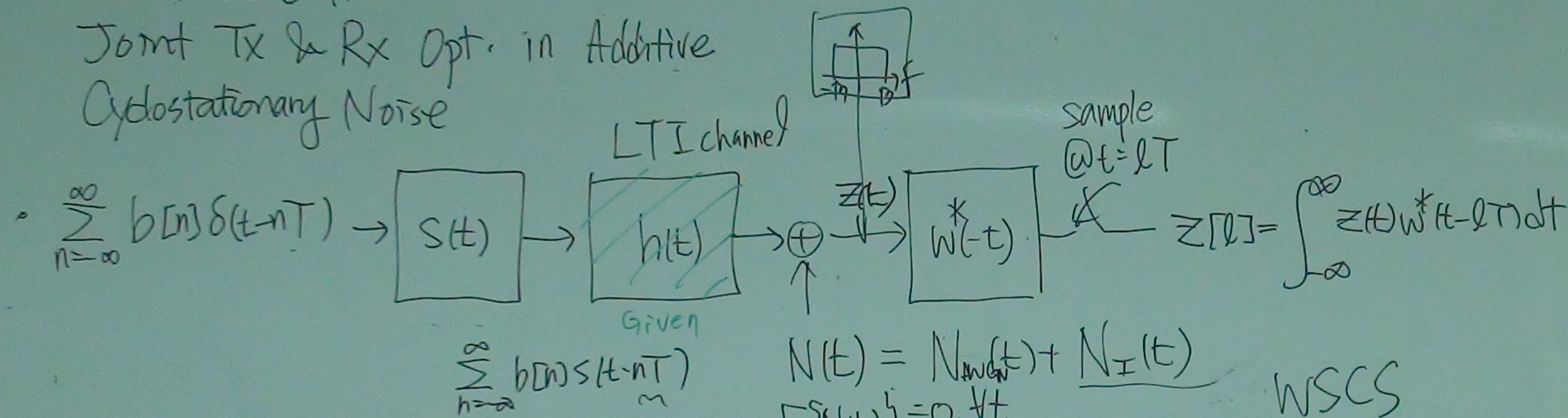
$$\Leftrightarrow \frac{1}{T} P^H(f) P(f) = I, \forall f$$

$$\Leftrightarrow \frac{1}{T} \sum_k |p_k(f - \frac{k}{T})|^2 = 1, \forall f$$



□ T-IT 2004.

Joint Tx & Rx Opt. in Additive Cyclostationary Noise



$$N(t) = N_{\text{AWGN}}(t) + N_{\text{I}}(t)$$

$$E\{N(t)\} = 0, \forall t$$

$$R_{N_{\text{I}}}(t, t_2) = R_{N_{\text{I}}}(t, t_2 + T, t_2 + T)$$

$$\tilde{R}_{N_{\text{I}}}(t, t_2) = 0, \forall t, t_2$$

WSCS

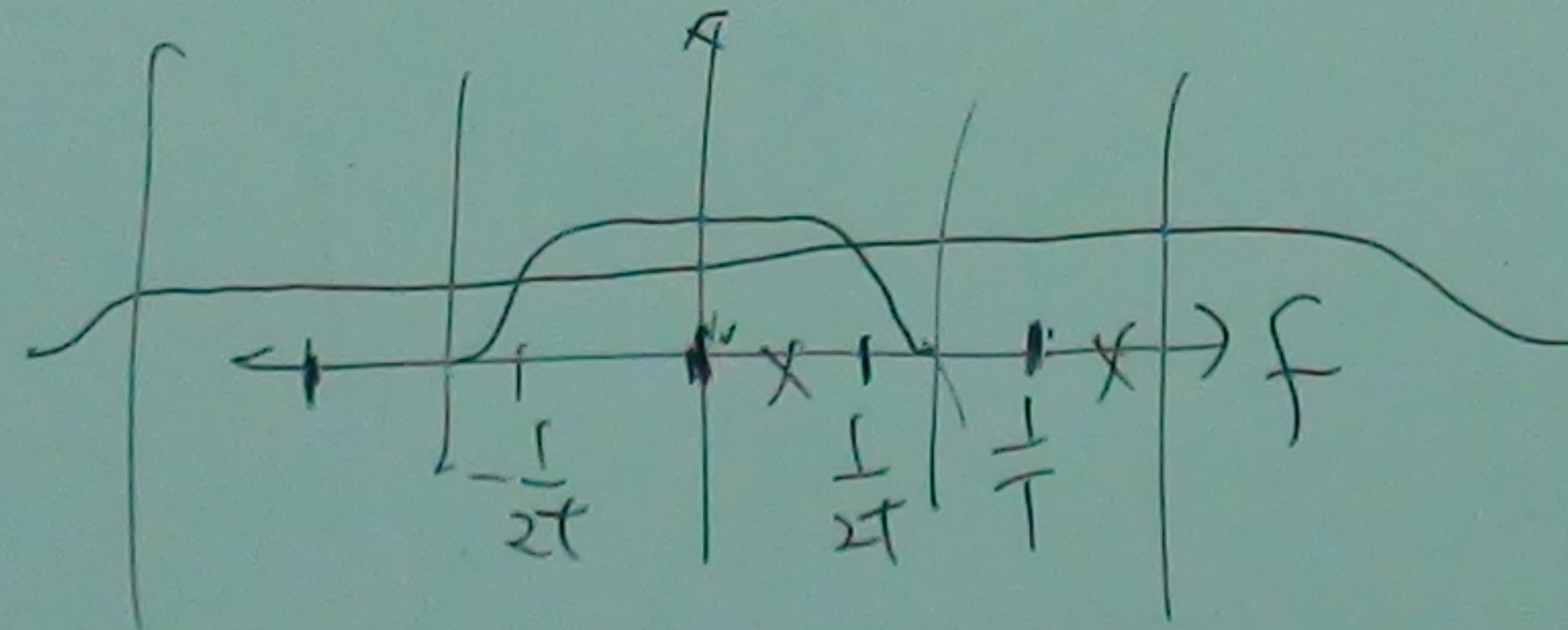
Find $S(t)$ & $w(t)$ s.t.

$$\min_{S(t), w(t)} E \{ \|b[n] - z[n]\|^2 \}$$

Subject to

$$\int_{-\infty}^{\infty} |S(f)|^2 df = 1$$

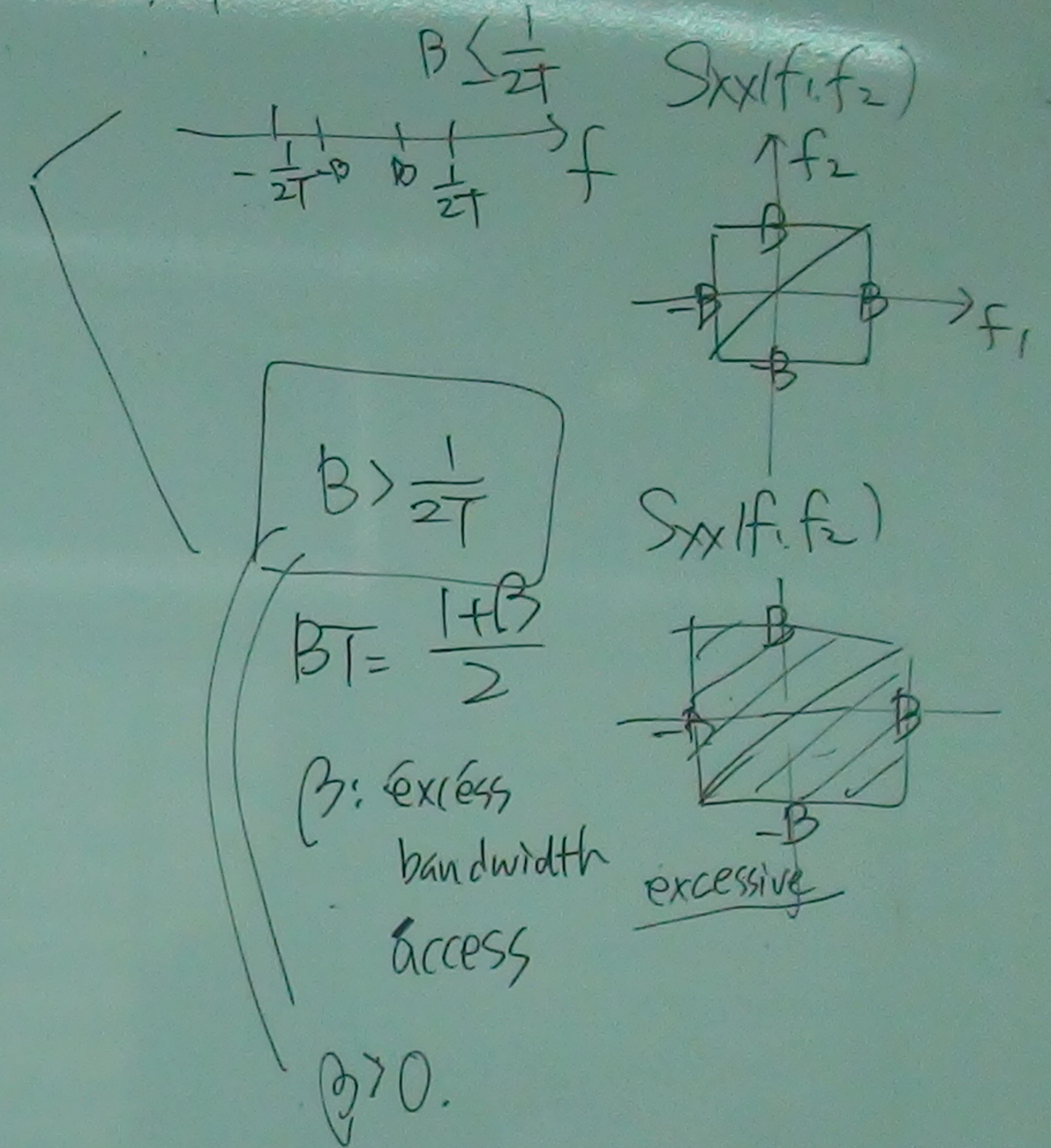
$$\int_{-B}^B |w(f)|^2 df = 1$$



$$S_{xx}(f, f_2) = G(f) S_{xx}(f, f_2) G^*(f_2)$$

ideal LPF w/ BW B.

$B \ll 1/T$



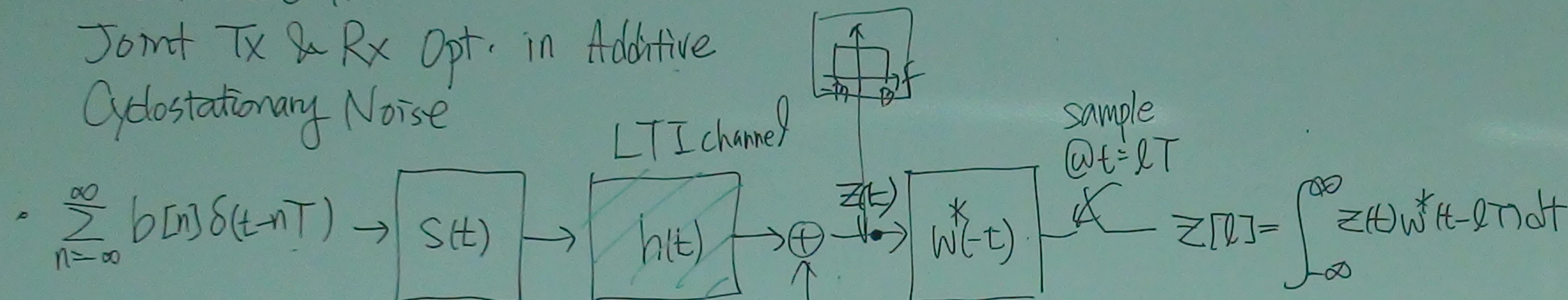
□ $\min_{S(t), w(t)}$ joint opt

$\equiv \min_{S(t), w(t)} \min_{S(t), w(t)} E \{ \|b[n] - z[n]\|^2 \}$ double opt



□ T-IT 2004.

Joint Tx & Rx Opt. in Additive Cyclostationary Noise



$$X(t) = \sum_{n=-\infty}^{\infty} b[n] \delta(t-nT)$$

$$N(t) = N_{\text{noise}}(t) + N_{\text{I}}(t)$$

$$E\{N(t)\} = 0, \forall t$$

$$R_{NN}(t, t_2) = R_{NN}(t, t_2 + T, t_2 + T)$$

$$\tilde{R}_{NN}(t, t_2) = 0, \forall t, t_2$$

WSS

$b[n]$ r.p. $E\{b[n]\} = 0, \forall n$
proper complex r.p.

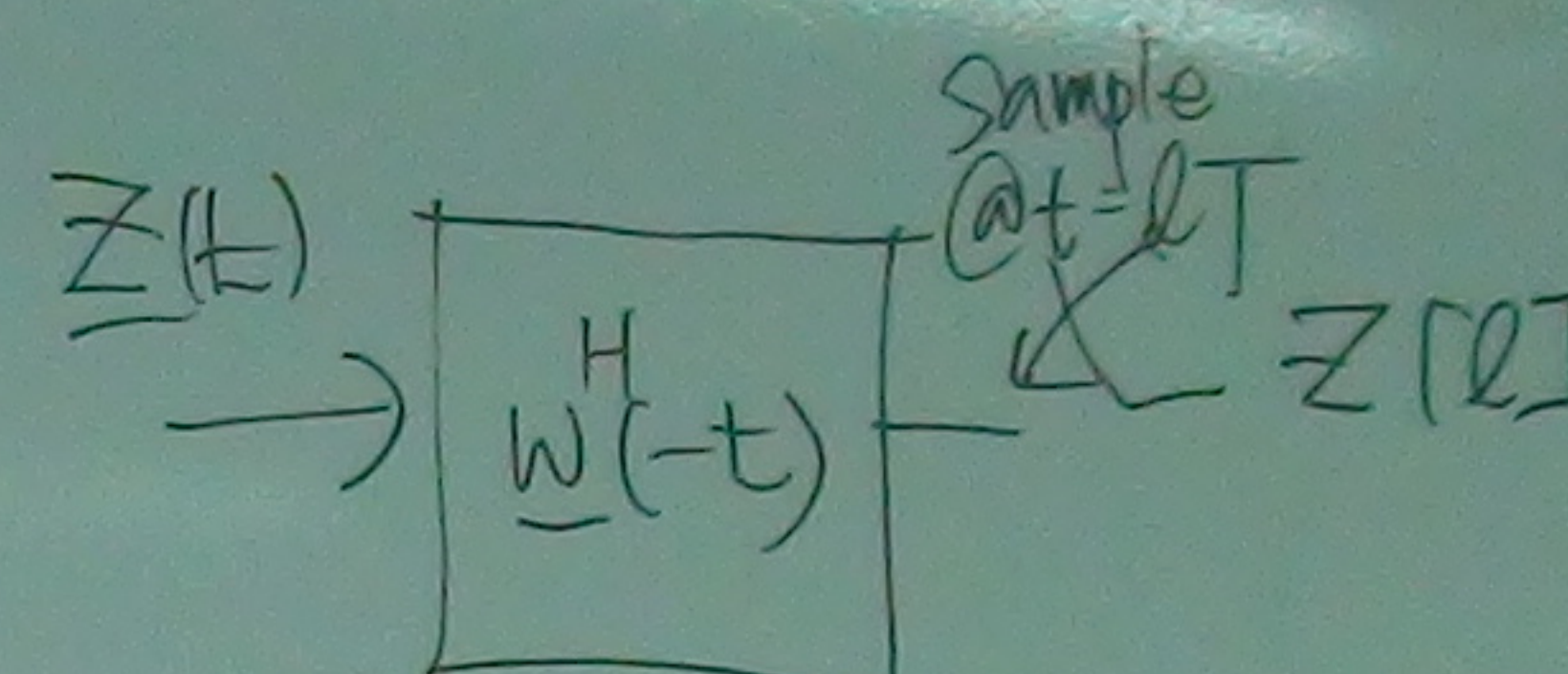
$$E\{b[n+k] b^*[n]\} = m[k], \text{ WSS}$$

$$E\{\|b[l] - z[l]\|^2\}, \text{ irrelevant to } l$$

• Conversion.

$$Z(t) \rightarrow \begin{bmatrix} F_v \\ B_v \end{bmatrix} \rightarrow Z(t)$$

Rx:



Signal

$$z[l] = \int_{-\infty}^{\infty} \frac{W^H(t-lT)}{W(t-lT)} z(t) dt$$

$$= \int_{-\infty}^{\infty} W^*(f) e^{j2\pi f l T} Z(f) df$$

$$= \int_{-\infty}^{\infty} W^H(t-lT) z(t) dt$$

$$Z(t) = \text{diag}\{h(t)\} * X(t) + N(t)$$

$$= \text{diag}\{h(t)\} * \left(\sum_n b[n] \delta(t-nT) \right) + N(t) \quad (\text{MIMO rep.})$$



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$$\square \quad E \{ \|b[l] - z[l]\|^2 \} = \int_{-\frac{1}{2T}}^{\frac{1}{2T}} T \cdot M(e^{j2\pi fT}) \underline{w}^H(f) R(f) \underline{w}(f) - 2 \operatorname{Re} \{ \underline{w}^H(f) M(e^{j2\pi fT}) p(f) \} df$$

where $M(e^{j2\pi fT}) = \mathcal{F} \{ m[l] \}$

$$R(f) = R_N(f) + \frac{1}{T} M(e^{j2\pi fT}) \underbrace{p(f) p^H(f)}_{\text{rank-one matrix}} > 0, \forall f$$

$p(t) = h(t) * s(t)$ overall channel response
symbol waveform

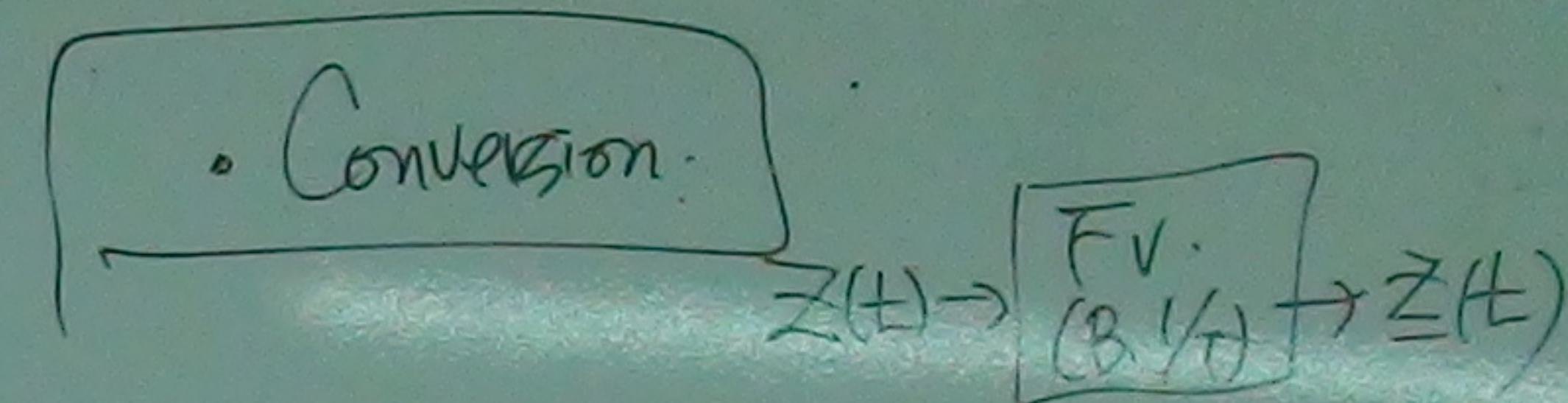
$$\begin{aligned} z(t) &= \sum_n b_n p(t - nT) + N(t) \\ \underline{z}(t) &= \sum_n \underline{b}_n \underline{p}(t - nT) + \underline{N}(t) \end{aligned}$$

FONC

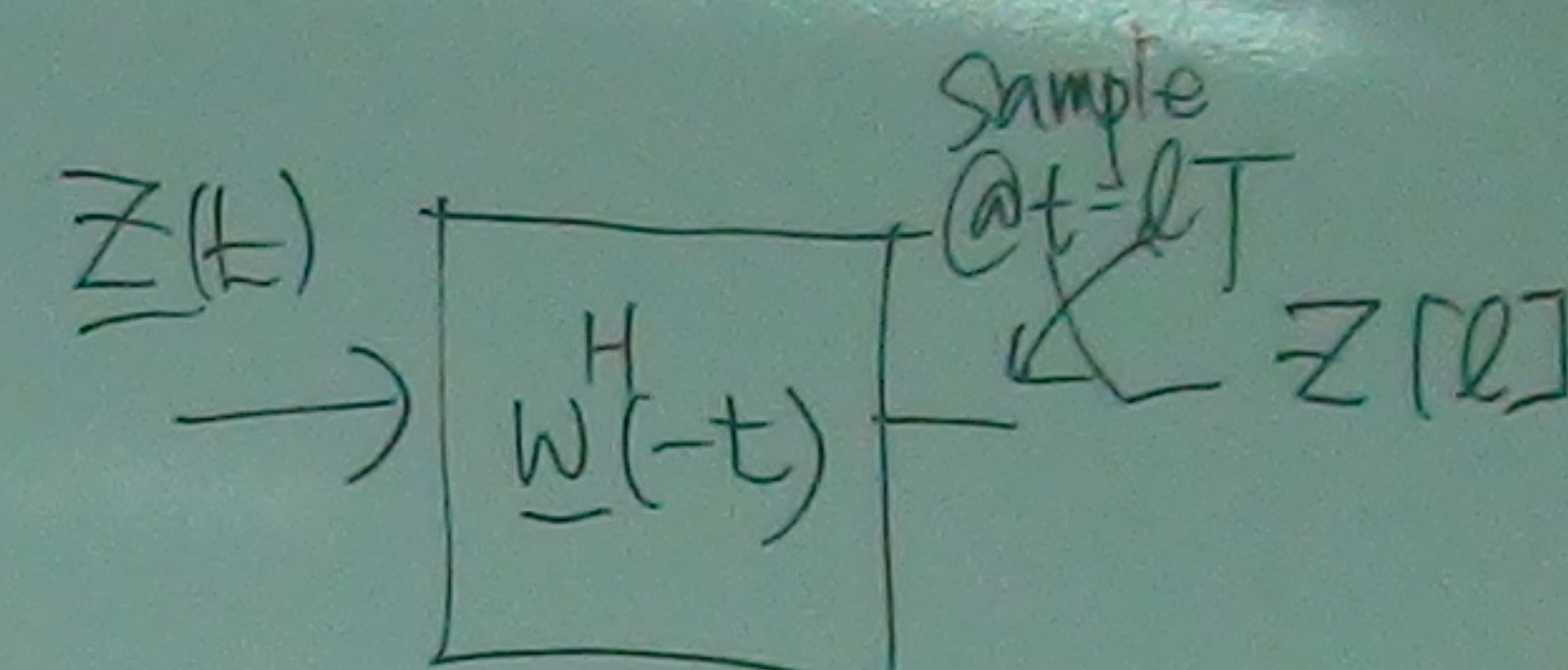
$$\left. \frac{2}{8 \underline{w}^H(f)} \right|_{\underline{w}(f) = \underline{w}_p(f)} = 0.$$

$$\Rightarrow \underline{2 R(f) \underline{w}(f) - 2 M(e^{j2\pi fT}) p(f)} = 0, \forall f$$

$$\Rightarrow \underline{w}(f) = M(e^{j2\pi fT}) R^{-1}(f) p(f), \forall f.$$



(i) Rx:



(ii) Signal

$$\begin{aligned} z[l] &= \int_{-\infty}^{\infty} \underline{w}^H(t - lT) \underline{z}(t) dt \\ &= \int_{-\infty}^{\infty} \underline{w}^H(f) e^{j2\pi f lT} \underline{z}(f) df \\ &= \int_{-\infty}^{\infty} \underline{w}^H(t - lT) \underline{z}(t) dt \end{aligned}$$

$$\begin{aligned} \underline{z}(t) &= \operatorname{diag} \{ \underline{h}(t) \} * \underline{x}(t) + \underline{N}(t) \\ &= \operatorname{diag} \{ \underline{h}(t) \} * \left(\sum_n \underline{b}_n \underline{s}(t - nT) \right) + \underline{N}(t) \quad (\text{MIMO rep.}) \end{aligned}$$

$$(iii) R_{NN}(t_1, t_2) = R_{NN}(\tau), \forall \tau = t_1 - t_2$$

$$S_{NN}(f) = R_{NN}(f)$$

